..19 Series Non-Contact Sensor

19 series is the state-of-the-art digital position transducer. It adopts the non-contact magnetrostrictive measuring technology for precise, accurate, and absolute measurement. The non-contact feature provides exceptional ease of installation and guarantees almost unlimited mechanical life expectancy.

This special sensor was designed for use in harsh environments, such as petrochemical, oil refinery, and power plant, with high contamination and presence of dust. 19 series has a wide variety of signal output selection included analog, serial digital and fieldbus interfaces.



high precision with extreme reliability...

Digital Fieldbus Connection...

This professional series adopts the noncontact magnetostrictive technology for precise, direct and absolute position feedback. Output signals include:

- Programmable analog output
- Start/Stop pulse interface
- Synchronous serial SSI interface
- CANbus
- Profibus
- DeviceNet
- EtherCAT













Order Code

The 19 series order code cosists of two parts: output code and installation code

For example, select the preferred output signal such as SSI and then choice the suitable installation profile such as hydraulic rod (H) $\,$



For example: SSI output with hydraulic rod (H)





high precision & reliability...

Specifications

Order Code
utput
leasurement Type
leasured Variables
esolution
epeatability
on-Linearity
odate Time
nput Voltage
put Protection
Power Consumption
ielectric Strength
Connector Type
Operation Temp.
Sealing
/ibration Rating
Shock Rating
EMC

Magnet Assigment



When using dual magnets, there is a minimum distance of 76mm need to be kept in between.

Diagnostic Display



Green	Red	Description
ON	OFF	Normal function
ON	ON	Magnet not detected

Integrated LEDs provide basic visual feedback for normal sensor operation and troubleshooting.

Programming Tools



Order Code	1700 951 018
Discription	19 Series Analog Programming Tool

The 19 series analog programming tool can be used to set the "zero" and "end" values anywhere within the nominal factory stroke range. Output

1 9 X X X X X X X X X X X

3 or 7 digits

1 Output / 1 Magnet Position	2 Outputs / 2 Magnets Position
001 = 0 - 10V	002 = 0 - 10V,0 - 10V
011 = 10 - 0V	012 = 10 - 0V,10 - 0V
021 = 0 - 5V	022 = 0 - 5V
031 = 5 - 0V	032 = 5 - 0V
041 = -10 - +10V	042 = -10 - +10V
051 = -5 - +5V	052 = -5 - +5V
101 = 4 - 20mA	102 = 4 - 20mA
111 = 20 - 4mA	112 = 20 - 4mA
121 = 0 - 20mA	122 = 0 - 20mA
131 = 20 - 0mA	132 = 20 - 0mA
141 = 0 - 24mA	142 = 0 - 24mA
151 = 24 - 0mA	152 = 24 - 0mA

2 Outputs / 1 Magnet (Position + Velocity)

003 xxx.x = 0 - 10V (Position), 0(Mini. Velocity) - 10V (Max. Velocity)
013 xxx.x = 10 - 0V (Position), 0(Mini. Velocity) - 10V (Max. Velocity)
103 xxx.x = 4 - 20mA (Position), 4(Mini. Velocity) - 20mA (Max. Velocity)
113 xxx.x = 20 - 4mA (Position), 4(Mini. Velocity) - 20mA (Max. Velocity)

— Velocity range: 0.001 - 10m/s Sample: 0 - 5.5m/s = 0 - 10V, code = 0030055

19 series sensor is preconfigured at the factory by model code designation. If needed, we offer programming tools for modifying sensor stroke and output types.

Connection Type

D60 = 6 pin male receptacle M16 (Connector not included) R02 = 2m PVC Direct Cable, Option: R01-R10 (1-10m) H02 = 2m PUR Direct Cable, Option: H01-H10 (1-10m)



R02 = 2m PVC Direct Cable, Option: R01-R10 (1-10m)

H02 = 2m PUR Direct Cable, Option: H01-H10 (1-10m)

Pin Assignments for 190 / 191

		D60 Pin	Cable
	1	Output 1	Black
	2	DC Gnd	White
(0,0)	3	Output 2	Yellow
\ 000	4	DC Gnd	Green
	5	+24 Vdc	Red
	6	0 Vdc	Blue

(View toward sensor pins)

Cable shield connects to connector shell and grounded at controller side.

Pin Assignments for 193

	D60 Pin	Cable
 1	Stop (-)	Black
2	Stop (+)	White
3	Start (+)	Yellow
4	Start (-)	Green
5	+24 Vdc	Red
6	0 Vdc	Blue

(View toward sensor pins)

Cable shield connects to connector shell and grounded at controller side.

Logic Diagram for 193 Start / Stop



Specifications

Order Code	192			
Output	SSI			
Measurement Type	Linear displacement			
Data Format	Binary or Grey			
Data Length	8 - 32 bits			
Data Speed	Cable Length: <3 <50 <100			
	Baud rate : 1000 <400 <300 <200 <100 kBd			
Update Time	Measuring Length : 300 750 1000 2000 5000 mm			
	Measurement/sec : 3.7 3.0 2.3 1.2 0.5 kHz			
— 14				
Resolution	Displacement: $1/2/5/10/20/50/100 \mu\text{m}$			
Repeatability	$< \pm 0.001\%$ of full scale (minimum $\pm 2.5\mu$ m)			
Non-Linearity	$< \pm 0.01\%$ of full scale (minimum ± 4.0400 mm)			
Update Time	0.5 ms up to 1200 mm / 1.0 ms up to 2400 mm			
	2.0 ms up to 4800 mm / 5.0 ms up to 7600 mm			
1				
Input Voltage	+24 Vac (20.4 - 28.8 Vac)			
Input Protection	Polarity protection up to -30Vdc, Over voltage protection up to 36Vdc			
Power Consumption	100mA (stroke range dependent)			
	500Vac (DC ground to machine ground)			
Connector Type	D70 Male			
Operation Temp				
Operation Temp.	-40 to 75°C, Humility 90% non-condensing			
Sealing	IP 67 (with connector)			
Shock Deting	100g eingle bit per LEC standard 68 2 27			
Shock Rating	100g single hit per IEC standard 68-2-27			
EMC	Emission En 00000-0-3, minunity En 01000-0-2, En 01000-4-2/3/4/0			
Timing Diagram	Sensor Input			
	Optocupler clocks interval 910hms 7mA			
	min. 48μs Clock (+)			
+Clock				
+Data				
MSB X				
	910hms			
Logic Diagram				
	Sensor Controller			
	\downarrow			

+24Vdc

0V

192 x x x x x x x x x

Data Length						
1 = 25 bits						
2 = 24 bits						
Output Forma	t					
B = Binary						
G = Grey Code						
Resolution						
1 = 5µm	2 = 10µm					
3 = 50µm	4 = 100µm					
5 = 20µm	6 = 2µm					
8 = 1µm						
Function						
1 = Standard					-	
Options						
00 = Measurir	ng direction forw	ard				
01 = Measurir	na direction reve	erse				

Remark: Direction forward means position reading become larger while magnet move away from electronic carriage. Direction backward means position reading become smaller while magnet move away from electronic carriage.

Connection Type

D70 = 7 pin male receptacle M16 (Connector not included) R02 = 2m PVC Direct Cable, Option: R01-R10 (1-10m) H02 = 2m PUR Direct Cable, Option: H01-H10 (1-10m)

Pin Assignments

		D70 Pin	Cable
	1	Data (-)	Black
6 7	2	Data (+)	White
$\left(\begin{array}{cc} \bullet & \bullet \end{array} \right)$	3	Clock (+)	Yellow
4 5	4	Clock (-)	Green
U	5	+24 Vdc	Red
	6	0 Vdc	Blue
	7	N.C.	

(View toward sensor pins)

Cable shield connects to connector shell and grounded at controller side.

Diagnostic Display



Green	Red	Description
ON	OFF	Normal function
ON	ON	Magnet not detected

Integrated LEDs provide basic visual feedback for normal sensor operation and troubleshooting.

Specifications

Order Code	194
Output	CANBus
Measurement Type	Linear displacement
Data Protocol	CANopen: CIA Standard DS-301 V3.0
	CANbasic: CAN 2.0A
Baud Rate	Baud rate : 1000 800 500 250 125 50 20 Kbit
	Cable length : <25 <50 <100 <250 <500 <1000 <2500 m
Resolution	CANopen CANbasic
- Displacement	5μm 2μm 5μm 2μm
- Speed	0.5mm/s 0.2mm/s 1.0mm/s 0.1mm
Repeatability	< ±0.001% of full scale (minimum ±2.5µm)
Non-Linearity	< ±0.01% of full scale (minimum ±40µm)
Update Time	0.5 ms up to 1200 mm / 1.0 ms up to 2400 mm
	2.0 ms up to 4800 mm / 5.0 ms up to 7600 mm
Input Voltage	+24Vdc (20.4 - 28.8Vdc)
Input Protection	Polarity protection up to -30Vdc, Over voltage protection up to 36Vdc
Power Consumption	100mA (stroke range dependent)
Dielectric Strength	500Vdc (DC ground to machine ground)
Connector Type	D60 Male
Operation Temp	40 to 75% . Use the $00%$ representation
Sooling	-40 to 75 C, Humility 90% hon-condensing
Vibration Dating	IP 67 (WITh connector)
Shock Rating	Emission EN 62000 6.2. Immunity EN 61000 6.2. EN 62000 4.2/2/4/6
EMC	Emission EN 68000-6-3, Immunity EN 61000-6-2, EN 68000-4-2/3/4/6

Diagnostic Display



D60 / D61 Connection



D62 Connection

Green	Red	Description
ON	OFF	Normal function
ON	ON	Magnet not detected

Integrated LEDs provide basic visual feedback for normal sensor operation and troubleshooting.

Pin Assignments



	D60/D61 Pin	Cable
1	CAN (-)	Black
2	CAN (+)	White
3	N.C.	Yellow
4	N.C.	Green
5	+24 Vdc	Red
6	0 Vdc	Blue

(View toward sensor pins)

Cable shield connects to connector shell and grounded at controller side.

Order Code	(Output	Code)
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1 9 4 X X X X	Х	Х	Х	Х	Х	Х	Х	
Protocol 101 = CANbasic 207 = Multi-Position CANbasic 304 = CANopen								
1 = 1000 kBit/s 2 = 500 kBit/s 3 = 250 kBit/s 4 = 125 kBit/s Resolution								
$1 = 5\mu m$ $4 = 10\mu m$ $2 = 2\mu m$ $5 = 20\mu m$ Connection Type	_						F	≀en :ust
D60 = 6 pin male receptacle M16 with termination resistor D61 = 6 pin male receptacle M16 D62 = 2 x 6 pin male receptacle M16 R02 = 2m PVC Direct Cable, Option: R01-R10 (1-10m) H02 = 2m PUR Direct Cable, Option: H01-H10 (1-10m)		1						
Magnet Number								

 Baud Rate
 Cable Length

 1000 Kbd
 25M

 500 Kbd
 100M

 250 Kbd
 250M

 125 Kbd
 500M

Remark: CANbus protocol parameters are chosen by customer and controller, not decided by Germanjet.

Z__ = 02 - 03 pcs of Magnet (If output 207 is selected)

Network Topology

Bus Network Topology



Star Network Topology







Specifications

195
Profibus-DP digital output
Linear displacement
Profibus-DP (EN-50 170)
Profibus-DP System according ISO 74498
Max 12Mbit/s
Position: 5µm/ other values selectable via GSD file
< ±0.001% of full scale (minimum ±2.5µm)
< ±0.01% of full scale (minimum ±40µm)
0.5 ms up to 1200 mm / 1.0 ms up to 2400 mm
2.0 ms up to 4800 mm / 5.0 ms up to 7600 mm
+24Vdc (20.4 - 28.8Vdc)
Polarity protection up to -30Vdc, Over voltage protection up to 36Vd
100mA (stroke range dependent)
500Vdc (DC ground to machine ground)
D62 / D53
-40 to 75°C, Humility 90% non-condensing
IP 67 (with connector)
15g / 10-2000Hz / IEC standard 68-2-6
100g single hit per IEC standard 68-2-27

Order Code (Output Code)

1 9 5 X X X X X X X X X X	XXX
Connection Type	
D62 = 2 x 6 pin male receptacle M16	
D53 = 1 x 5 pin male receptacle M12 1 x 5 pin female receptacle M12 1 x 4 pin male receptacle M8 (Connector not included)	
Input Voltage	
1 = +24Vdc	
Output	
P102 = Profibus-DP with 1 Magnet Measurement (Standard)	
P101 = Profibus-DP with Multi-Magnet Measurement	
Magnet Number	
Z = 02 - 03 pcs of Magnet (If output P101 is selected)	

Profibus Interface

The 19 series Profibus-DP interface fulfill the requirement of EN50170. The position transducer adopts the non-contact magnetostrictive measuring technology with direct transmission of RS-485 standard in a baud rate of 12 Mbits/s. Profibus wiring uses shielded twisted pair cable and can be used to connect up to 32 devices in a single segment (piece of cable).

D62 multi-drop connector outlet and D60 connector outlet with bus termination are available. Profibus provides useful functions for diagnostics and configuration by loading the GSD (Electronic Device Data Sheet) into the bus. The file is available to be downloaded at

Profibus Addressing

Normally addressing is done by Profibus SetSlaveAddress. If some master systems do not support this standard, or customers controller can not handle, direct addressing is recommended.

D62 Pin Assignments



D62 Connection

D53 Pin Assignments



D53 Connection



(View toward sensor pins)

Cable shield connects to connector shell and grounded at controller side.



M12 female M12 male (View toward sensor pins)

1	N.C.
2	RxD/TxD-N(Bus)
3	N.C.
4	RxD/TxD-P(Bus)
5	Cable Shield
	*only apply to female receptacle



Power Male Receptacle

Network Topology





Terminator

Receptacle	Order Code
D53	1800 951 043
D62	1800 951 028

Diagnostic Display

Green	Red	Description
ON	OFF	Normal function
ON	ON	Magnet not detected

Integrated LEDs provide basic visual feedback for normal sensor operation and troubleshooting.



Specifications

Order Code	196			
Output	DeviceNet digital output			
Measurement Type	Linear displacement			
Data Protocol	DeviceNet 2.0 Version			
Output Signal	CAN FieldBus System ISO 11898			
Baud Rate	Baud rate : 500 250 125 Kbit/s			
	Cable length : <100 <250 <500 m			
Resolution	2μm or 5μm			
Repeatability	< ±0.001% of full scale (minimum ±2.5µm)			
Non-Linearity	< ±0.01% of full scale (minimum ±40µm)			
Update Time	0.5 ms up to 1200 mm / 1.0 ms up to 2400 mm			
	2.0 ms up to 4800 mm / 5.0 ms up to 7600 mm			
Input Voltage	+24Vdc (20.4 - 28.8Vdc)			
Input Protection	Polarity protection up to -30Vdc, Over voltage protection up to 36Vdc			
Power Consumption	100mA (stroke range dependent)			
Dielectric Strength	500Vdc (DC ground to machine ground)			
Connector Type	D60 Male			
Operation Temp.	-40 to 75°C, Humility 90% non-condensing			
Sealing	IP 67 (with connector)			
Vibration Rating	15g / 10-2000Hz / IEC standard 68-2-6			
Shock Rating	100g single hit per IEC standard 68-2-27			

100g single hit per IEC standard 68-2-27 Emission EN 68000-6-3, Immunity EN 61000-6-2, EN 68000-4-2/3/4/6

Order Code (Output Code)

EMC

	1 9	6 X	XX	X	X	X	X	Х	Х
Hardware									
2 = Standard									
Output Protocol									
02 = DeviceNet									
Baud Rate									
2 = 500 kBit/s									
3 = 250 kBit/s									
4 = 125 kBit/s									
Resolution									
1 = 5µm									
2 = 2µm									
Туре									
1 = Standard						_			
Connection Type									

D60 = 6 pin male receptacle M16 with termination resistor D61 = 6 pin male receptacle M16

Remark: DeviceNet protocol parameters are chosen by customer and controller, not decided by Germanjet.

Diagnostic Display

Green	Red	Description
ON	OFF	Normal function
ON	ON	Magnet not detected

Integrated LEDs provide basic visual feedback for normal sensor operation and troubleshooting.

Pin Assignments



	D60/D61 Pin
1	CAN (-)
2	CAN (+)
3	N.C.
4	N.C.
5	+24 Vdc
6	0 Vdc

(View toward sensor pins)

Cable shield connects to connector shell and grounded at controller side.

DeviceNet Protocol

DeviceNet is layered on top of the CAN (Controller Area Network) technology and takes advantage of CAN, making it low-cost and robust. DeviceNet supports maxinium 500 Kbit/s data rates. Position resolution can be up to 2μ m. Nodes are distributed along a DeviceNet network by the means of a trunkline-dropline topology. Nodes can be easily removed and added to reduce production downtime, increase network flexibility, and decrease troubleshooting time.

The DeviceNet installation is quick and easy. Each sensor is provided with an Electronical Data Sheet (EDS). All sensor parameters are installed into the network using the EDS file. The file is available to be downloaded at <u>www.germanjet.de</u>.

A PC programming tool, such as DeviceNet Manager offered by Rockwell Automation, is used to set the node identifier and baud rate. (Factory node setting is 63 and the baud rate is 500 Kbit/s)

advance fieldbus technology ...

Specifications

Order Code	197
Output	EtherCAT
Measurement Type	Linear displacement
Data Protocol	100 Base-Tx, Fast Ethernet
Output Signal	Simultaneous multi-position and velocity measurements up to 3 magnets
Baud Rate	Max. 100Mbit/s
Resolution	Position: 1 to 1000µm selectable / Velocity: 1µm/s depend on velocity and stre
Repeatability	< ±0.001% of full scale (minimum ±2.5µm)
Non-Linearity	< ±0.01% of full scale (minimum ±50µm)
Update Time	0.5 ms up to 1200 mm / 1.0 ms up to 2400 mm
	2.0 ms up to 4800 mm / 5.0 ms up to 7600 mm
Input Voltage	+24Vdc (20.4 - 28.8Vdc)
Input Protection	Polarity protection up to -30Vdc, Over voltage protection up to 36Vdc
Power Consumption	100mA (stroke range dependent)
Dielectric Strength	500Vdc (DC ground to machine ground)
Connector Type	D56
Operation Temp.	-40 to 75°C, Humility 90% non-condensing
Sealing	IP 67 (with connector)
Vibration Rating	15g / 10-2000Hz / IEC standard 68-2-6
Shock Rating	100g single hit per IEC standard 68-2-27
EMC	Emission EN 68000-6-3, Immunity EN 61000-6-2, EN 68000-4-2/3/4/6

Order Code (Output Code)



EtherCAT Interface

The 19 series EtherCAT interface fulfill the requirement of EtherCAT 100 Base-Tx standard. EtherCAT (Ethernet for Control Automation Technology) is the state-of-the-art interface developed by Beckhoff Automation. This interface is supported by EtherCAT Technology Group.

D62 Pin Assignments



D56 Connection



(View toward sensor pins)

M12 female

M12 female

 1
 Tx +

 2
 Rx +

 3
 Tx

 4
 Rx



Power Male Receptacle

Network Topology



Diagnostic Display	

Green	Red	Description
ON	OFF	Normal function
ON	ON	Magnet not detected

Integrated LEDs provide basic visual feedback for normal sensor operation and troubleshooting.

Order Code (Installation Code)





Installation

6 = Dia. 60mm ring









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Mounting

- 1 = 42.5mm mounting
- 2 = 42.5mm isolation mounting
- 3 = 50mm mounting

Magnet Type

- 1 = Captive
- 2 = Floating
- 3 = Die-cast
- 4 = Large floating

Installation





Order Code (Installation Code)



tention :

The ring magnet should not intouch with the sensor rod.

The bore in the piston rod is dependent on the hydraulic pressure and the pistons velocity. The minimum drilling should be 13mm. Do not exceed the peak pressure.

The sensor rod should be protected against wear.

Installation Instrustion



Bore in cyclinder dia. 10-20mm to push single wires with connector through



- 37 -

Order Code (Installation Code)





Dimensions



Profibus D62 / D53

Total sensor length tolerances are :

<8000mm stroke lengths, +8mm tolerance

>8000mm stroke lengths, +15mm/-5mm tolerance

* Tolerances of total length have no influence for the measuring stroke length



The flexible style is required to be supported inside a guide straight or bent pipe made of non-ferrous material. When installed inside a pressure housing pipe, the sensor is suitable for use in hydraulic cyclinders. The flexible style is housed in a Teflon coated stainless steel for full protection against outside agents for use in harsh environments with high contamination.



Installation Dimensions

Stroke length <8000mm, front dead zone is 50mm Stroke length >8000mm, front dead zone is 130mm



Pressure housing pipe for ID 10mm flange : Pipe OD <10mm Pipe ID > 8mm

Stroke Length < 8000mm - Pipe Length = Stroke Length + 150mm

Stroke Length > 8000mm - Pipe Length = Stroke Length + 230mm

Stroke length <8000mm, front dead zone is 50mm Stroke length >8000mm, front dead zone is 130mm



Pressure housing pipe for ID 12.7mm flange : Pipe OD <12.7mm Pipe ID > 8.5mm

Stroke Length < 8000mm - Pipe Length = Stroke Length + 150mm

Stroke Length > 8000mm - Pipe Length = Stroke Length + 230mm

* Select Dia. 60mm ring magnet or High floating magnet

Installation Instrustion

In urgent situation, 19F can be delivered immediately and economically on site to shorten unexpected machine downtime.



Connection example with thread

19F is placed inside a guide pipe made of non-ferrous material.

10mm dia. housing pipe mounting Order code: 1900951002 (Install for every 500mm)

Welding can be applied

to accommodate the connection.

M18x1.5 flange external mounting

Order code: 1900951003





An installation of 7600mm long of 19F for 6600 ton two plated plastic injection machine.

